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# Experimental results and EMC considerations on RFID location systems

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## Experimental results and EMC considerations on RFID location systems

1. Introduction
2. RFID Location Systems
3. The RFID Radar positioning system
4. Performance evaluation based on experimental results
5. EMC Measurements
6. Conclusions

# Experimental results and EMC considerations on RFID location systems

## 1. Introduction

- RFID Active / Passive
- Readers – microprocessor based
- Tags – memories
- Multiple frequency bands
- Standardized

### 2. RFID Location Systems

- Inertial systems – good for outdoor applications
- Indoor locations: triangulation / scene analysis / proximity

1. Specialized infrastructure
2. Using wireless networks signals and information
3. Mixed

- Many implementations

Active Badge, Cricket, MotionStar, MSR Radar,  
RFID Radar, SmartFloor, SpotON

## Experimental results and EMC considerations on RFID location systems

### 3. The RFID Radar positioning system

Catalog data:

Operating frequency: 870 MHz / 10kHz band

Max. range: 40 / 100 m

Passive / Active tags

5uW / 200uW tags

Passive TTF – Tag Talk First protocol

RS232 interface

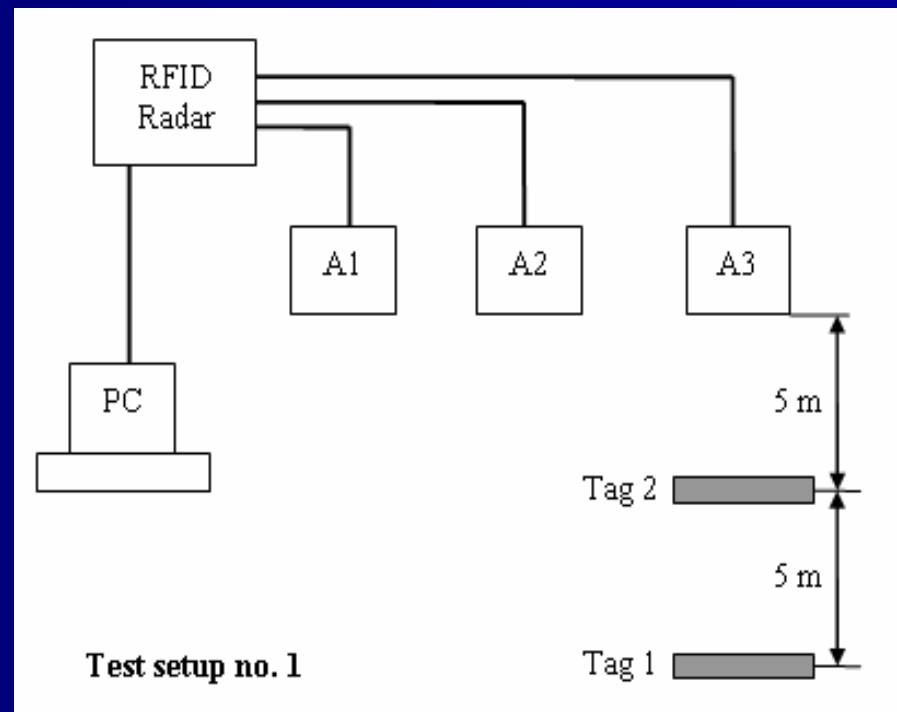
Control software



# Experimental results and EMC considerations on RFID location systems

## 4. Performance evaluation based on experimental results

Indoor test setup 1  
Same setup for  
1.000 measurements  
3 different days



# Experimental results and EMC considerations on RFID location systems

## 4. Performance evaluation based on experimental results

Results

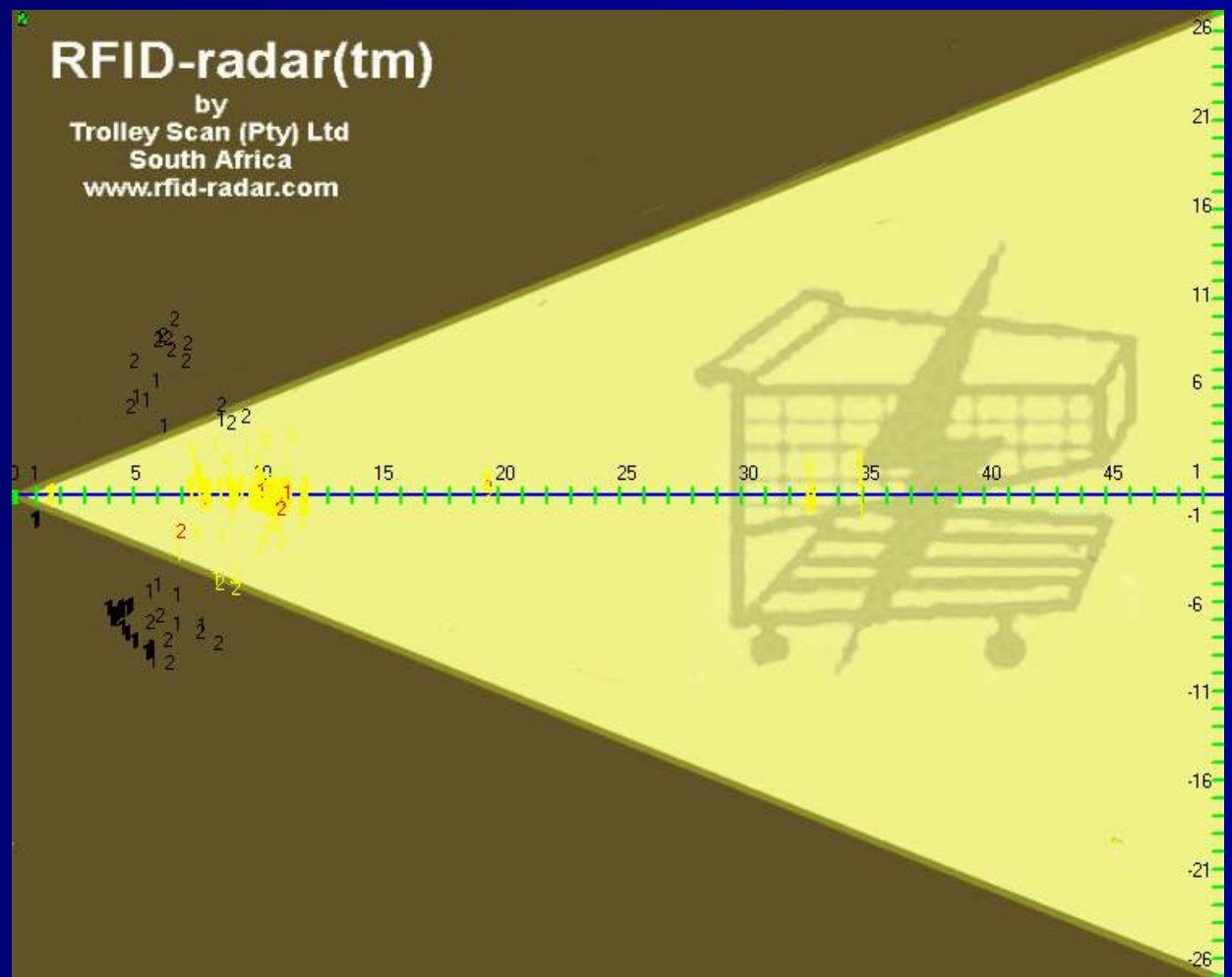
65 % of total

Error < 10%



Tag 1 at 5m

Tag 2 at 10 m

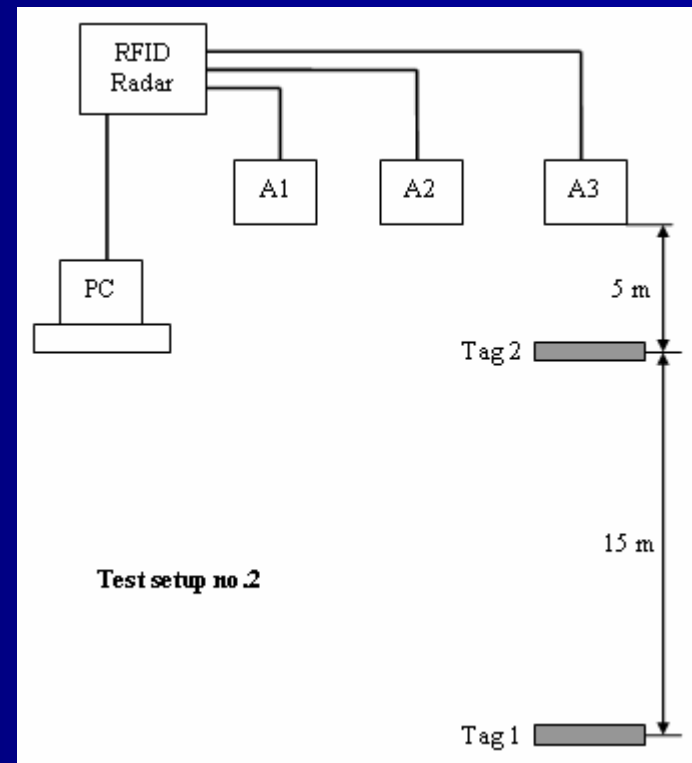


## Experimental results and EMC considerations on RFID location systems

### 4. Performance evaluation based on experimental results

Indoor test setup 2

Same setup for  
1.000 measurements  
3 different days





# Experimental results and EMC considerations on RFID location systems

## 4. Performance evaluation based on experimental results

Results

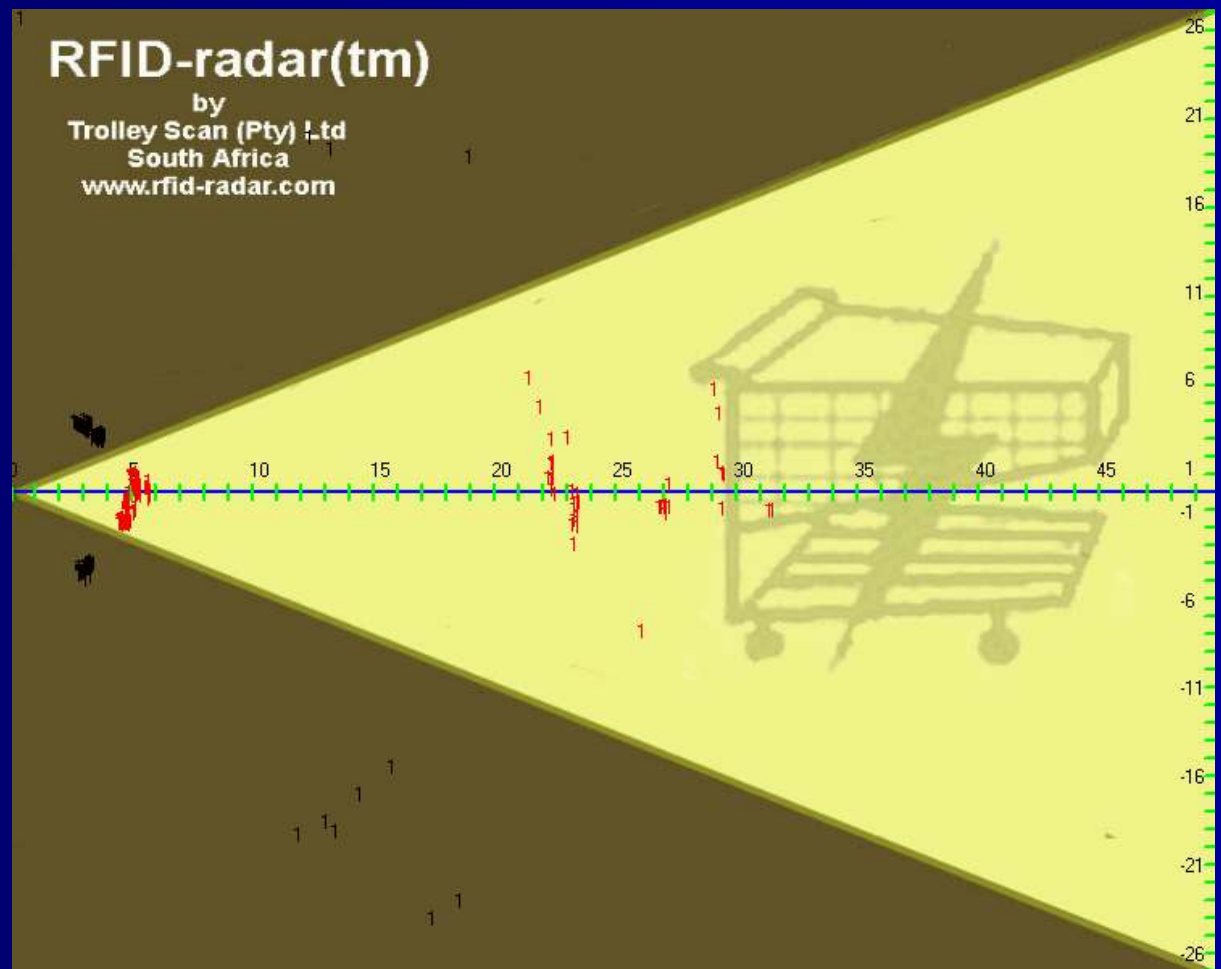
35 % of total

Error < 10%



Tag 1 at 5m

Tag 2 at 10 m

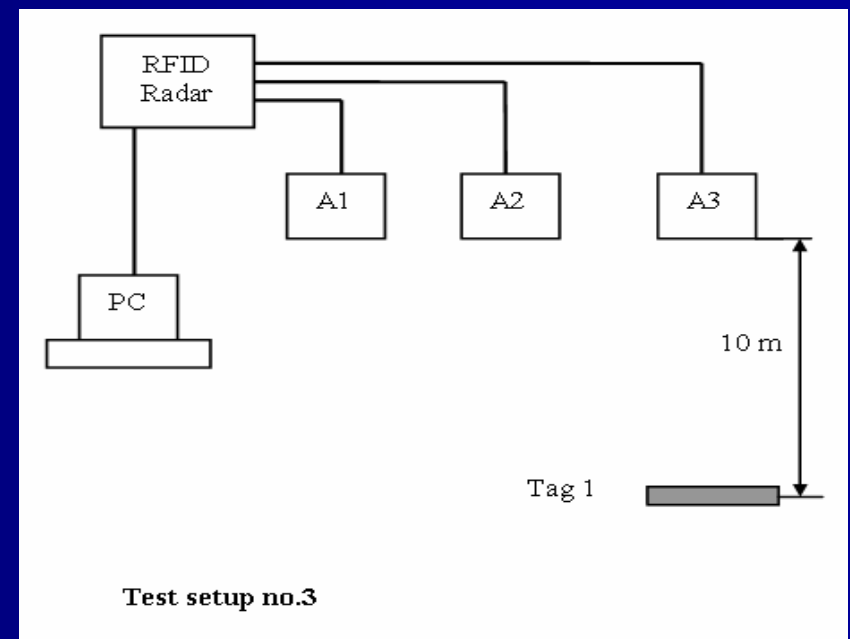


## Experimental results and EMC considerations on RFID location systems

### 4. Performance evaluation based on experimental results

Outdoor test setup 3

Same setup for  
1.000 measurements  
3 different days



# Experimental results and EMC considerations on RFID location systems

## 4. Performance evaluation based on experimental results

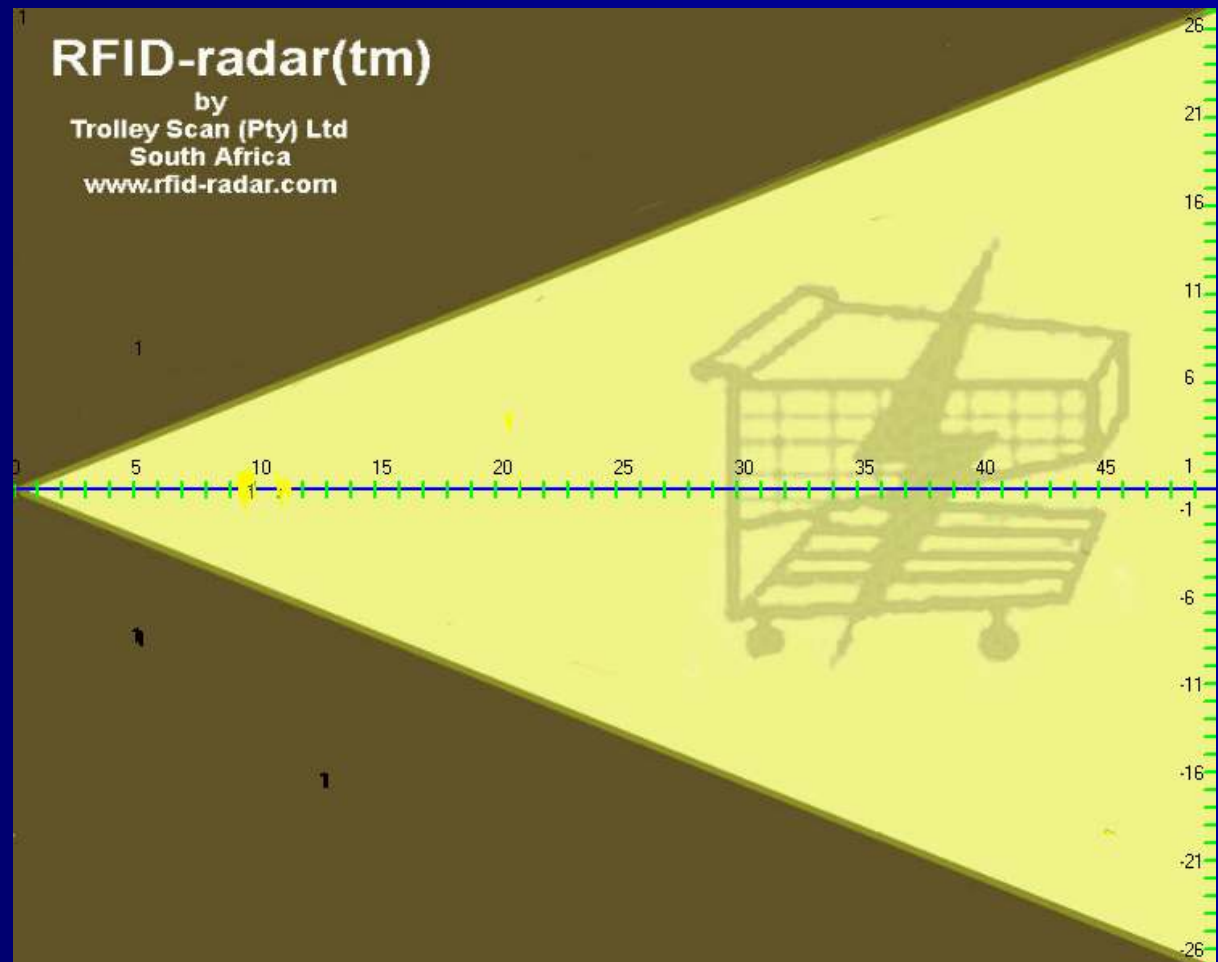
Results

6 % of total

Error > 10%



Tag 1 at 10 m



## Experimental results and EMC considerations on RFID location systems

### 5. EMC Measurements

#### SRM-3000 NARDA

- ✓ Indoor / Outdoor measurements
- ✓ Noise floor 10 ... 20 mV/m
- ✓ Frequency band 100 kHz – 3 GHz
- ✓ Isotropic Three-axis antenna (75 MHz – 3 GHz)

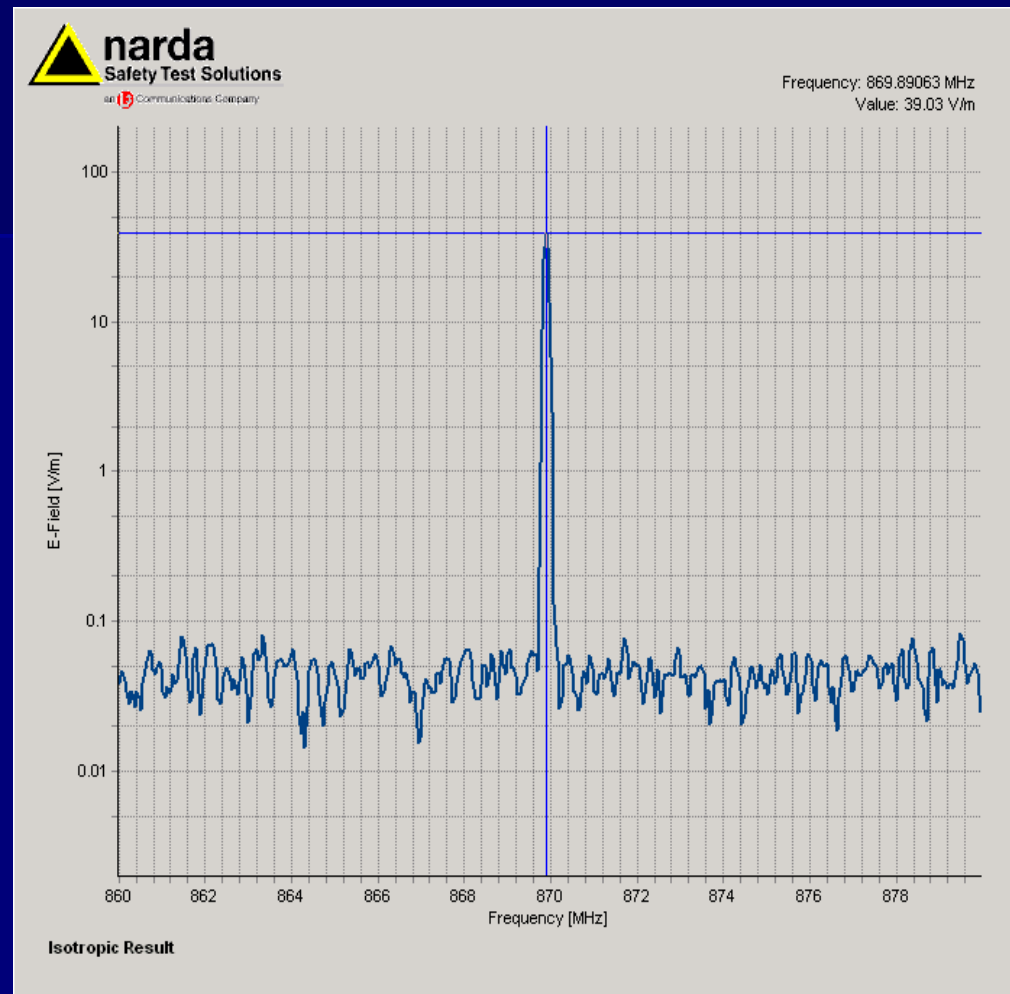


# Experimental results and EMC considerations on RFID location systems

## 5. EMC Measurements

Central frequency = 869.89 MHz

Peak E value = 39.03 V/m



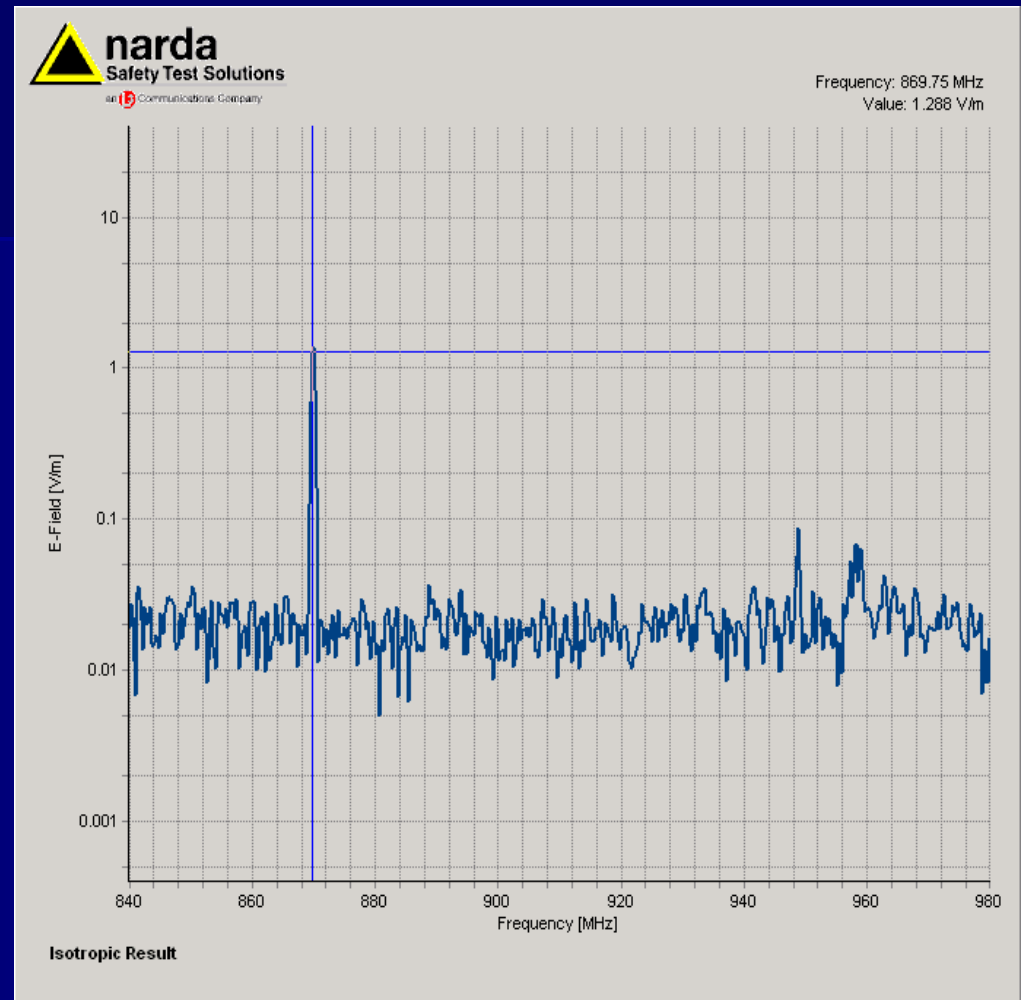
Electric field magnitude at 3m distance in front of the antenna

# Experimental results and EMC considerations on RFID location systems

## 5. EMC Measurements

Central frequency = 869.75 MHz

Peak E value = 1.288 V/m



Electric field magnitude at 20 m distance in front of the antenna

### CONCLUSIONS

#### Performances

1. Performances greatly affected by interferences
2. Only 40 to 60 percent of total measurements under 10 % accuracy
3. Not suitable for high-precision applications
4. Small errors in open-areas – 93 % accuracy

#### EMC aspects

1. NOT suitable for indoor applications – high E field
2. Very good for long-range outdoor positioning applications

A lot of work to do in the future !

**Thank you !**

**Q u e s t i o n s ?**